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... 4.10 * Existence and Unicity of Solutions 151 4.11 Summary 153
4.12 Notes and References 153 4.13 Exercises 154 5. Describing
Function Analysis 157 ... 5.7 Exercises 188 Part II: Nonlinear Control
Systems Design 191 Introduction to Part II 191 6. Feedback
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Exercises in Nonlinear Control Systems

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4 Chapter 1 Exercise 1.2 The behavior of a dynamical system is described by the equation $\dot{x}(2) + 1.5x(1) + 0.5x_2 + f_2x_2 + [x(1)]^2g_1 = 2 = 0$: (1) Determine the region of x , such that $X = 0$ is an exponentially stable equilibrium point of the given system. Solution. Denote $x_1 = x$; $x_2 = x(1)$, and $X = [x_1; x_2]^T$. Hence, we have

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